## Math 254 Exam 1 Solutions

1. Carefully state the definition of "basis". Give two examples for the vector space  $\mathbb{R}^2$ .

A basis is a set of vectors that is independent, with the added property that any additional vector will make the set dependent. Two examples in  $\mathbb{R}^2$ are  $\{(1,0), (0,1)\}$  (the standard basis), and  $\{(2,2), (3,0)\}$  (this was proved independent in Chapter 0 Problem 6).

2. Let  $u = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ , and  $v = \begin{bmatrix} -1 & 5 & 2 \end{bmatrix}$ . For each of the following expressions, determine

what type they are (undefined, scalar, matrix/vector). (a) uvu, (b) uvv, (c)  $(u \cdot v) \cdot v$ , (d)  $(u \times v) \cdot u$ , (e)  $(u \times v) \times u$ 

 $u ext{ is } 3 \times 1$ .  $v ext{ is } 1 \times 3$ .  $uv ext{ is defined; it is } a 3 \times 3$  matrix. Therefore,  $(uv)u ext{ is defined, and is } a 3 \times 1$  matrix (a). However,  $uv ext{ has } 3$  columns but  $v ext{ has only } 1$  row, so  $(uv)v ext{ is undefined (b)}$ . We may also consider  $u, v ext{ as } 3$ -vectors; in this case,  $u \cdot v ext{ is defined, and is a scalar. However, <math>(u \cdot v) \cdot v ext{ is not defined, } since ext{ dot product is not between a scalar and a vector (c). } u \times v ext{ is defined, } since ext{ both } u, v ext{ are } 3$ -vectors; it is itself a 3-vector. Therefore,  $(u \times v) \cdot u ext{ is defined, } since ext{ both } vectors ext{ in the dot product are the same size. Its result is a scalar (d). In addition, <math>(u \times v) \times u ext{ is also defined, since both vectors in the (second) cross product are 3-vectors. Its result is a 3-vector (e).$ 

3. For  $u = \begin{bmatrix} -3 & 5 & 2 \end{bmatrix}$  and  $v = \begin{bmatrix} 4 & 2 & 1 \end{bmatrix}$ , determine whether u, v are orthogonal. Justify your answer.

$$u \cdot v = (-3)4 + (5)2 + (2)1 = -12 + 10 + 2 = 0$$
. Therefore  $u, v$  are orthogonal.

4. For 
$$A = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 2 & 3 \end{bmatrix}$$
, and  $B = \begin{bmatrix} 2 & 1 \\ 0 & -1 \\ 1 & 6 \end{bmatrix}$ , calculate  $AB$  and  $BA$   
$$AB = \begin{bmatrix} 0 & -11 \\ 3 & 16 \end{bmatrix}, BA = \begin{bmatrix} 2 & 1 & -1 \\ 0 & -2 & -3 \\ 1 & 12 & 16 \end{bmatrix}$$

5. For  $\vec{u} = (1, 2, 1)$  and  $\vec{v} = (-3, -1, 0)$ , find  $\vec{u} \times \vec{v}$  and  $\vec{v} \times \vec{u}$ .

$$\begin{split} \vec{u} \times \vec{v} &= (\hat{i} + 2\hat{j} + \hat{k}) \times (-3\hat{i} - \hat{j}) = -(\hat{i} \times \hat{j}) - 6(\hat{j} \times \hat{i}) - 3(\hat{k} \times \hat{i}) - (\hat{k} \times \hat{j}) = \\ -\hat{k} - 6(-\hat{k}) - 3\hat{j} - (-\hat{i}) &= (1, -3, 5) \\ \vec{v} \times \vec{u} &= (-3\hat{i} - \hat{j}) \times (\hat{i} + 2\hat{j} + \hat{k}) = -6(\hat{i} \times \hat{j}) - 3(\hat{i} \times \hat{k}) - (\hat{j} \times \hat{i}) - (\hat{j} \times \hat{k}) = \\ -6\hat{k} - 3(-\hat{j}) - (-\hat{k}) - \hat{i} &= (-1, 3, -5) \end{split}$$

Note: This is no coincidence; it turns out that  $(u \times v) = -(v \times u)$  for ALL 3-vectors u, v.