

## Math 254 Fall 2014 Exam 7 Solutions

1. Carefully state the definition of “linearly dependent”. Give two different linearly dependent sets from  $P_1(t)$ .

A set of vectors is linearly dependent if a nondegenerate linear combination yields the zero vector. Examples:  $\{1, 2\}$ ,  $\{1, t, 1 + t\}$ . Common errors: not a set, not from  $P_1(t)$ .

2. Prove that  $f(x) = x^{-1/2}$  is in  $L^1(0, 1)$  but not in  $L^3(0, 1)$ .

$L^1$ :  $\int_0^1 |f(x)|^1 dx = \int_0^1 x^{-1/2} dx = \lim_{m \rightarrow 0^+} 2x^{1/2}|_m^1 = \lim_{m \rightarrow 0^+} 2 - 2\sqrt{m} = 2$ . Since this is finite,  $f(x) \in L^1(0, 1)$ .

$L^3$ :  $\int_0^1 |f(x)|^3 dx = \int_0^1 x^{-3/2} dx = \lim_{m \rightarrow 0^+} -2x^{-1/2}|_m^1 = \lim_{m \rightarrow 0^+} -2 + \frac{2}{\sqrt{m}} = \infty$ . Since this doesn't converge,  $f(x) \notin L^3(0, 1)$ .

The remaining problems all concern the inner product on  $\mathbb{R}^3$  defined by  $\langle x, y \rangle_A = x^T A y$ , where  $A$  is the positive definite matrix  $\begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 1 & 2 \end{pmatrix}$ . Set  $u = (1, 1, -2)^T$ ,  $v = (1, 2, -1)^T$ .

3. Calculate  $\langle u, u \rangle_A$ ,  $\langle v, v \rangle_A$ ,  $\langle u, v \rangle_A$ .

$$\langle u, u \rangle_A = (1 \ 1 \ -2) \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} = (1 \ 1 \ -2) \begin{pmatrix} 3 \\ 0 \\ -3 \end{pmatrix} = 9.$$

$$\langle v, v \rangle_A = (1 \ 2 \ -1) \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} = (1 \ 2 \ -1) \begin{pmatrix} 3 \\ 3 \\ 0 \end{pmatrix} = 9.$$

$$\langle u, v \rangle_A = (1 \ 1 \ -2) \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} = (1 \ 1 \ -2) \begin{pmatrix} 3 \\ 3 \\ 0 \end{pmatrix} = 6.$$

4. Use the Gram-Schmidt process to find an orthogonal basis for  $W = \text{Span}(u, v)$ .

Note: orthogonal means in the  $\langle \cdot, \cdot \rangle_A$  sense.

We build orthogonal basis  $\{w_1, w_2\}$  as follows: set  $w_1 = u$ , and  $w_2 = v - \text{proj}(v, w_1) = v - \frac{\langle v, w_1 \rangle_A}{\langle w_1, w_1 \rangle_A} w_1 = v - \frac{\langle v, u \rangle_A}{\langle u, u \rangle_A} u$ . We calculated these in (3), so  $w_2 = (1, 2, -1)^T - \frac{6}{9}(1, 1, -2)^T = (\frac{1}{3}, \frac{4}{3}, \frac{1}{3})^T$ . If desired, we can double-check that  $\langle w_1, w_2 \rangle_A = 0$ .

5. Let  $W = \text{Span}(u, v)$ . Find a nonzero vector in  $W^\perp$ . Note: This means in the  $\langle \cdot, \cdot \rangle_A$  sense.

Solution 1: Pick any vector, say  $z = (1, 0, 0)$ , not in  $W$ . Using the orthogonal basis from (4), we calculate  $z - \text{proj}(z, w_1) - \text{proj}(z, w_2)$ . We get  $z - \frac{3}{9}(1, 1, -2) - \frac{1}{5}(\frac{1}{3}, \frac{4}{3}, \frac{1}{3}) = (\frac{3}{5}, -\frac{3}{5}, \frac{3}{5})$ . If desired we can rescale to  $(1, -1, 1)$ .

Solution 2: We seek  $z = (a, b, c)$  to satisfy  $\langle z, u \rangle_A = \langle z, v \rangle_A = 0$ . This gives the homogeneous linear system  $\{3a - 3c = 0, 3a + 3b = 0\}$ , which has two pivots and a one-dimensional solution space. We can choose any one element from this space, such as  $(1, -1, 1)$ .